

$$\boldsymbol{E} = \frac{q\boldsymbol{r}}{4\pi\epsilon_0r^3} = \frac{q\hat{\boldsymbol{r}}}{4\pi\epsilon_0r^2}$$

$$\boldsymbol{E} = \iiint_V \frac{\rho(\boldsymbol{r}')\mathrm{d}v}{4\pi\epsilon_0} \cdot \frac{\boldsymbol{r} - \boldsymbol{r}'}{|\boldsymbol{r} - \boldsymbol{r}'|^3}$$

$$\varphi = \frac{q}{4\pi\epsilon_0r}$$

$$\varphi = \iiint_V \frac{\rho(\boldsymbol{r}')\mathrm{d}v}{4\pi\epsilon_0|\boldsymbol{r} - \boldsymbol{r}'|}$$

$$\nabla \cdot \boldsymbol{E} = \frac{\rho}{\epsilon_0}$$

$$\oiint_S \boldsymbol{E} \cdot \mathrm{d}\boldsymbol{s} = \frac{Q}{\epsilon_0}$$

$$\nabla \times \boldsymbol{E} = 0$$

$$\nabla\varphi = -\boldsymbol{E}$$

$$\nabla^2\varphi = -\frac{\rho}{\epsilon_0}$$

$$C = \frac{Q}{V}$$

$$\boldsymbol{p} = q\boldsymbol{d}$$

$$\varphi = \frac{\boldsymbol{p} \cdot \boldsymbol{r}}{4\pi\epsilon_0r^3}$$

$$\boldsymbol{E} = \frac{1}{4\pi\epsilon_0} \left(\frac{3(\boldsymbol{p} \cdot \boldsymbol{r})\boldsymbol{r}}{r^5} - \frac{\boldsymbol{p}}{r^3} \right)$$

$$E_{\parallel} = \frac{p}{4\pi\epsilon_0} \cdot \frac{3\cos^2\theta - 1}{r^3}$$

$$E_{\perp} = \frac{p}{4\pi\epsilon_0} \cdot \frac{3\sin\theta\cos\theta}{r^3}$$

$$E = \frac{p}{4\pi\epsilon_0} \cdot \frac{\sqrt{3\cos^2+1}}{r^3}$$

$$d_{xy} = 6ql_1l_2$$

$$\varphi_{xy} = \frac{3ql_1l_2xy}{4\pi\epsilon_0r^5}$$

$$d_{xx} = 6ql_1l_2 = 6q(b^2 - a^2)$$

$$\varphi_{xx} = \frac{q(b^2 - a^2)(3x^2 - r^2)}{4\pi\epsilon_0r^5}$$

$$\varphi^{(n)} \propto r^{-n-1}$$

$$\varphi = \frac{1}{4\pi\epsilon_0} \left(Q \cdot \frac{1}{r} - \boldsymbol{p} \cdot \nabla \frac{1}{r} + \frac{1}{6} \boldsymbol{D} : \nabla \nabla \frac{1}{r} - \dots \right)$$

$$Q = \iiint_V \rho(\boldsymbol{r})\mathrm{d}v$$

$$\boldsymbol{p} = \iiint_V \boldsymbol{r}\rho(\boldsymbol{r})\mathrm{d}v$$

$$\boldsymbol{D}_{ij} = \iiint_V (3\boldsymbol{r}_i\boldsymbol{r}_j - \delta_{ij}r^2)\rho(\boldsymbol{r})\mathrm{d}v$$

$$\nabla \nabla \frac{1}{r} = \frac{1}{r^5} \begin{bmatrix} 3x^2 - r^2 & 3xy & 3xz \\ 3xy & 3y^2 - r^2 & 3yz \\ 3xz & 3yz & 3z^2 - r^2 \end{bmatrix}$$

$$\boldsymbol{E} = \frac{\sigma}{\epsilon_0} \boldsymbol{n}$$

$$\boldsymbol{E}_{\text{surface}} = \frac{\sigma}{2\epsilon_0} \boldsymbol{n}$$

$$\omega^2 = \frac{n_0q_e^2}{\epsilon_0m_e}$$

$$U = \frac{1}{2} \iiint_V \varphi \rho \mathrm{d}v = \frac{\epsilon_0}{2} \iiint_V E^2 \mathrm{d}v$$

$$U = \frac{QV}{2} = \frac{CV^2}{2} = \frac{Q^2}{2C}$$

$$\boldsymbol{P} = Nq\boldsymbol{\delta}$$

$$\boldsymbol{P} = \chi\epsilon_0\boldsymbol{E}$$

$$\sigma_{\text{pol}} = \boldsymbol{P} \cdot \boldsymbol{n} = P \cos \theta$$

$$\rho_{\text{pol}} = -\nabla \cdot \boldsymbol{P}$$

$$\boldsymbol{D} = \epsilon_0\boldsymbol{E} + \boldsymbol{P}$$

$$\iiint_S \boldsymbol{D} \cdot \mathrm{d}\boldsymbol{s} = Q_{\text{free}}$$

$$\nabla \cdot \boldsymbol{D} = \kappa\epsilon_0\nabla \cdot \boldsymbol{E} = \rho_{\text{free}}$$

$$\boldsymbol{P} = \left(1 - \frac{1}{\kappa}\right) \boldsymbol{D} = (\kappa - 1)\epsilon_0\boldsymbol{E}$$

$$\boldsymbol{E} = \frac{q\boldsymbol{r}}{4\pi\kappa\epsilon_0r^3}$$

$$U = \frac{1}{2} \iiint_V \varphi \rho_{\text{free}} \mathrm{d}v = \frac{1}{2} \iiint_V \boldsymbol{D} \cdot \boldsymbol{E} \mathrm{d}v$$

$$\text{ball : } \begin{cases} E = \begin{cases} \frac{Qr}{4\pi\epsilon_0R^3} = \frac{\rho r}{3\epsilon_0}, & r \leq R \\ \frac{Q}{4\pi\epsilon_0r^2} = \frac{\rho R^3}{3\epsilon_0r^2}, & r > R \end{cases} \\ \varphi = \begin{cases} \frac{Q(3R^2 - r^2)}{8\pi\epsilon_0R^3} = \frac{\rho(3R^2 - r^2)}{6\epsilon_0}, & r \leq R \\ \frac{Q}{4\pi\epsilon_0r} = \frac{\rho R^3}{3\epsilon_0r}, & r > R \end{cases} \\ U = \frac{3Q^2}{20\pi\epsilon_0R} = \frac{4\pi\rho^2R^5}{15\epsilon_0} \end{cases}$$

$$\text{sphere : } \begin{cases} E = \begin{cases} 0, & r < R \\ \frac{Q}{8\pi\epsilon_0r^2} = \frac{\sigma R^2}{2\epsilon_0r^2}, & r = R \\ \frac{Q}{4\pi\epsilon_0r^2} = \frac{\sigma R^2}{\epsilon_0r^2}, & r > R \end{cases} \\ \varphi = \begin{cases} \frac{Q}{4\pi\epsilon_0R} = \frac{\sigma R}{\epsilon_0}, & r \leq R \\ \frac{Q}{4\pi\epsilon_0r} = \frac{\sigma R^2}{\epsilon_0r}, & r > R \end{cases} \\ U = \frac{Q^2}{8\pi\epsilon_0R} = \frac{2\pi\sigma^2R^3}{\epsilon_0} \end{cases}$$

$$\text{wire : } \begin{cases} E = \frac{\lambda}{2\pi\epsilon_0r} \\ \varphi = -\frac{\lambda \ln r}{2\pi} \end{cases}$$

$$\text{plate : } \begin{cases} E = \frac{\sigma}{2\epsilon_0} \\ C = \frac{\epsilon_0 S}{d} \\ U = \frac{Q^2 d}{2\epsilon_0 S} \\ \sigma_U = \frac{\sigma^2 d}{2\epsilon_0} \end{cases}$$

$$\text{cylinder : } \begin{cases} C = \frac{2\pi\epsilon_0 l}{\ln(r_2/r_1)} \\ U = \frac{Q^2}{4\pi\epsilon_0 l} \ln \frac{r_2}{r_1} \\ \lambda_U = \frac{\lambda^2}{4\pi\epsilon_0} \ln \frac{r_2}{r_1} \end{cases}$$

$$\sigma_0 \cos \theta : \begin{cases} \frac{\sigma_0}{3\epsilon_0} \boldsymbol{e}_x, & r < R \\ \frac{R^3\sigma_0}{3\epsilon_0} \frac{3\boldsymbol{r}_x\boldsymbol{r} - r^2\boldsymbol{e}_x}{r^5} = \frac{R^3\sigma_0}{\epsilon_0r^3} \left(\cos \theta - \frac{1}{3}, \cos \theta \sin \theta \right), & r > R \end{cases}$$